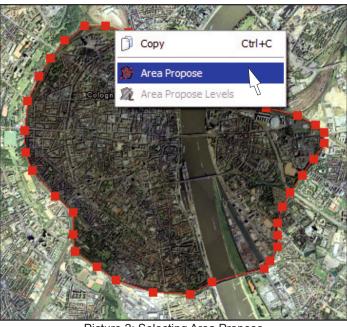


IGIplan

State-of-the-art Mission Planning Software

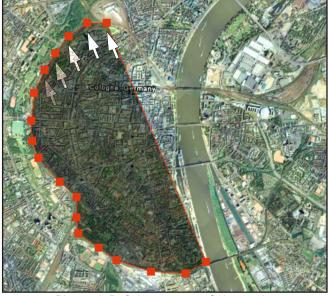
IGIplan is an advanced mission planning software. It supports over 600 local coordinate systems and all aerial cameras and sensors and is prepared for every kind of mission. Working together with the CCNS, flight missions can be planned and flown in one connected workflow. The intuitive graphical user interface and its real time computation of flight lines help the operator in his day-to-day business. As a special feature, IGI-plan includes GoogleEarth™ format support to show end-customers results in their familiar environment.



Picture 2: Selecting Area Propose

Features:

- More than 600 local coordinate systems
- Support for all common aerial cameras and sensors
- Raster & vector map support for common file formats
- Support for many DTM raster formats
- · Integrated world-wide DTM
- · Drag and modify flight lines interactively
- Automatic altitude determination through sensor specific mission planning parameters (GSD, picture scale)
- Planning and creation of flight lines, blocks or tracks with automatic levels using DTM
- Import of self-defined WMS servers
- Full support for IGI's CCNS
- 3D view of the flight plan
- GoogleEarth (*.kml) format support
- Multiple Undo / Redo
- Video tutorials



Picture 1: Defining an area - Cologne city

Example - Area Propose:

Plan your mission within a few minutes and only by two simple steps.

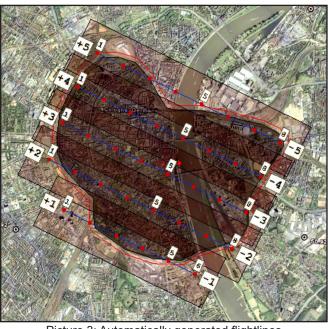
Step 1: Define a polygon by selecting an area

with the mouse.

Step 2: Choose Area Propose from the popup

menu

The flightlines are calculated automatically, and the resulting mission plan is shown.



Picture 3: Automatically generated flightlines

IGIplan[™] - Mission Planning Software

IGIplan Sensor Type Support		
		Automatic Altitude Determination & Coverage Simulation when changing:
Analog Cameras	e.g. RC10/20/30, RMK-A, RMK-TOP, LMK,	Picture scale, forward size, sidewards size
Digital Cameras	e.g. complete DMC, UltraCam, Digi- CAM, and PhaseOne camera series	Ground Sample Distance (GSD) and analog camera features
LiDAR Scanner	e.g. LiteMapper series	pts/sqm and speed, swath
Line Scanner	e.g. JAS, 3-DAS-1,	GSD, swath

System requirements:

Intel Pentium®, Core™ or equivalent processor Microsoft® Windows 10 & Windows 11 4 GB of RAM

Graphics system with complete OpenGL 2.1 implementation or higher
NVidia Quadro graphics card recommended

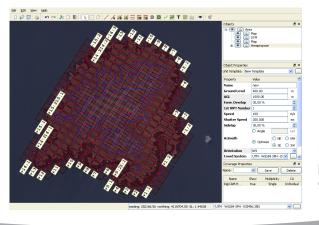
NVidia Quadro graphics card recommended 150 MB of available hard disk space

Keyhole Markup Language support:



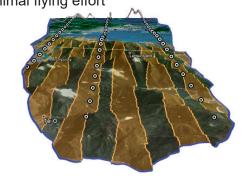


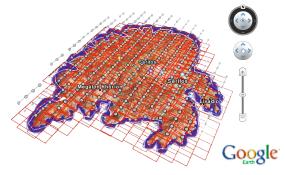
Import polygon from GoogleEarth to IGIplan.



Terrain Following:

- · Good overlap in the whole area
- · Minimal flying effort







Export resulting flightplan from IGIplan to GoogleEarth.



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